## Detection efficiency of the ESS Target Imaging System: Monte Carlo simulations

Nicolò Borghi Esben Klinkby, Bent Lauritzen, Luca Zanini

AccApp '17, Quebec City - August 3rd, 2017

 $f(x+\Delta x) = \sum_{i=0}^{\infty} \frac{(\Delta x)^{i}}{i!} f^{(i)}(x) = a^{i}$ 

DTU Nutech Center for Nuclear Technologies

### Outline

#### • The ESS target imaging system

- Motivation and goals
- Principle of target imaging
- Proposed realization
- Neutronic simulations

#### Target image reconstruction

- Methods and approximations
- Monte Carlo simulations
- Preliminary results

#### • Status and outlook

- Code development
- Test rig

#### The ESS target imaging system Motivation and goals



### The ESS Target Wheel...

- 2.5 m diameter
- suspended on a 6 m long shaft
- 36 sectors of 10° each
- 7000 tungsten bricks (3 tons)
- 2500 tons of shielding steel around

### ...will operate in extreme conditions

- 3 MW heat deposit from 5 MW proton beam
- 2.86 ms long proton pulses with 4% duty cycle
- 7 million 100°C thermal cycles per year

#### The ESS target imaging system Motivation and goals

Tungsten bricks operate in a **brittle regime** after exposure to radiation

- Conditions may induce the cleaving of the tungsten bricks
- Local reconfiguration or accumulation of small debris may result in the **blocking of the coolant channels**
- Thermal and pressure stresses may not be relieved, affecting the actual lifetime of the target wheel



#### Important to know from an operations perspective if the tungsten geometry is preserved over the 5 years of expected lifetime of the target wheel

#### The ESS target imaging system Principle of target imaging



**Activation** of the tungsten bricks is mainly due to hadrons.

The **spatial distribution** of the decay gammas can be imaged through the target vessel.

The is TIS intended to provide high spatial resolution imaging of the decay gammas from the target wheel.

The image of the target **inner structure** can be used to confirm the **correct operation conditions.** 

# The ESS target imaging system **Proposed realization**

- Brick size: 1×3×8 cm<sup>3</sup>
- Width of cooling channels: 0.2 cm
- Required maximum spatial resolution: 0.1 cm
- Gamma emission collimated by means of a 2.8 m steel block with syncopated 1x1 mm<sup>2</sup> grooves to ensure complete radial coverage of the wheel
- Azimuthal coverage achieved by means of the wheel rotation
- An array of scintillators is placed on top of the collimator block
- Scintillators **coupled to optical fibers** to convey the scintillation light to a high-sensitivity I-sCMOS camera



# The ESS target imaging system **Neutronic simulations**





Simulation workflow:

- MCNPX simulation with protons on the first sector
- CINDER'90 to calculate nuclide inventory after 1 s on the first sector
- Gamma source (bricks+vessel) copied to the imaged sector
- MCNPX simulation to calculate the **gamma flux** at scintillators
- Independent MCNPX simulation for gamma and neutron background evaluation



#### Target image reconstruction Methods and approximations

Target imaging is done in **two stages**:

- Normal operation: full-arc, time-averaged acquisition for each individual sector;
- High-resolution operation: narrow gating **contouring** the problematic spot.

During high-resolution operation, **onchip data accumulation** across successive rotations is performed to limit the final readout noise.



#### Target image reconstruction Methods and approximations



The first implementation of the code is based on **two approximations**:

- **thin-layer (2D)**: given the attenuation length for 686 keV photons in tungsten, **only the top cm** is responsible for the measured signal;
- **cell rejection**: the collimator allows only gammas perpendicular to the target surface to reach the scintillators, so **no blurring** is included in the simulations.

#### Target image reconstruction Monte Carlo simulations



The code is fully-integrated with the ROOT framework:

- Bricks and impurities are instances of TBox objects, thus 3D-ready;
- No limit to the number, position or shape of the simulated objects;
- Collimators are instances of TArc objects grouped into a **TH2D** (**r**, *θ*) **histogram**.

#### Target image reconstruction Monte Carlo simulations

From the objects in the geometry, a Probability Distribution Function is defined:

- points, corresponding to emitted gammas, are sampled uniformly within the domain (wheel segment);
- hits in the detectors (arcs) are recorded if the sampled point is within the a brick or impurity;
- the number of sampled points is proportional to the **TIS acquisition time**;
- by default, the **specific activity** of each object is the same, i.e. impurities are fragments of the spallation tungsten;
- the relative intensity of the emission from each object can be adjusted to simulate different materials;



#### Target image reconstruction Preliminary results



After the chosen exposure time (2 days), the collected image (left) is compared to a **higher-statistics ideal image** (right) obtained from a clean PDF, representing a healthy target.



#### Target image reconstruction Preliminary results



The images are compared by means of the **Pearson's**  $\chi^2$  **homogeneity test**, which calculates the probability for the **hypothesis of identity** to hold. The analysis of the **normalized residuals** locates the anomalous bins and the **Q-Q plot** estimates the probability for the residuals fluctuations to be normally distributed.



# Target image reconstruction **Preliminary results**



Increasing the number of angular bins (7 bins) and iterating the  $\chi^2$  test allows to **identify the location of the anomaly** and provides a **2D reconstruction** of the imaged target sector. The image spatial resolution is proportional to the number of angular bins.

#### Target image reconstruction Preliminary results

DTU

Probability of anomaly recognition



The Pearson's test is a statistical estimator and its reliability must be evaluated to **avoid false positive errors**:

- after 1h of acquisition, the test is not able to identify any of the anomalies introduced (14%);
- after 10h, the probability of getting a reliable answer is 41%;
- after 1d, the probability is increased to 65%;
- above 2d of acquisition, the adopted test is completely reliable.

#### Status and outlook Code development



The code presented is the first step in the development of an **image reconstruction and anomaly detection protocol** and will serve as the basis for the future design of the TIS data acquisition software. However, several aspects of the image reconstruction methodology require further investigation:

- introduce background and noise effects;
- simulate impurities of different size and specific activity;
- automate the algorithm for blind analysis (splitting and re-iteration);
- randomize the anomaly placement to fully test the blind analysis procedure;
- implement **different statistical checks** to cross-verify the Pearson's test;
- introduce a realistic **description of the camera gating**, mainly in terms of dead-time and maximum achievable fps.

#### Status and outlook Test rig



A **test-rig** specifically designed for the DTU <sup>60</sup>Co Terabalt source is currently under construction and will be used as a **proof of principle** for the imaging system.

The **gamma intensity** of the <sup>60</sup>Co source is comparable to that of the ESS target wheel.

It will allow to perform tests under conditions **relevant to the actual ESS system**.

DTU

# Status and outlook Test rig

The test-rig will give the opportunity to investigate several aspects:

- **Spatial resolution** of the system: 1 mm, 0.5 mm grooves and several resolution targets on the wheel
- Scintillator and fiber efficiency in detection and transmission of the signal (losses due to attenuation, couplings and connections, radiation damage, etc.)
- Heating elements and temperature sensors to study the **signal degradation** at ESS operating conditions

#### • Gating techniques and software controls:

- Intelligent gating
- Signal processing
- Image reconstruction
- ( LabView for device controls (motors, encoders, sensors, heating elements, etc.)

### Thank you for your attention

#### Nicolò Borghi

DTU Nutech - Technical University of Denmark

nicbo@dtu.dk

DTU Risø Campus Building 201 Frederiksborgvej 399 4000, Roskilde - Denmark